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Distributed Amplifier Multi-Axis Servo Control System for Custom Engineered Motion Systems

Automation1 FLEX

Control Without Compromise

Simplify cable management and reduce control cabinet electronics for your Aerotech custom-engineered motion system with Automation1 FLEX. FLEX includes a central controller with up to four field-mounted axis modules. Each axis module includes a power amplifier and low-latency feedback signal serialization. The power amplifiers share a common power supply, and the serialized feedback signal is transported over the glass optical fiber HyperWire FLEX network.

This distributed approach means fewer electronics in your control cabinet and less point-to-point wiring in your cable management system eliminating failure points and reducing the burden of bulky cable carriers. FLEX's fast proprietary protocol can use the serialized encoder signals in our Position Synchronized Output (PSO) feature. For cleanroom designs, FLEX reduces overall particulate generation.

Automation1

FLEX is a part of the user-friendly Automation1 motion control platform, which includes the following:

- Development Software
- Controls
- Motor Drives
- Fiber-Optic HyperWire[®] Communication Bus



KEY FEATURES:

- Daisy-chain signals to MINIMIZE CABLE MANAGEMENT
- Field-mounted axes modules REDUCE
 CABINET SPACE
- Centralized FLEX CONTROLLER connects to 4 axis modules
- AXES MODULES include power amplifiers & feedback signal processing
- LOW-LATENCY serialized axis feedback
- High-flex GLASS OPTICAL FIBER cables
- Works with encoder-based POSITION SYNCHRONIZED OUTPUT (PSO)

AUTOMATION1 FLEX CONTROLLER GENERAL SPECIFICATIONS

CATEGORY	SPECIFICATION
Maximum Supported Number of Axis Modules	4
Control Supply	24 VDC
Motor Supply ⁽¹⁾	Single-phase 0-240 VAC; 50/60 Hz
Bus Supply Voltage ⁽¹⁾	0-340 VDC
Position Synchronized Output (PSO)	Standard: • One-axis PSO (includes one-axis Part-Speed PSO)
	Optional: • Two-axis PSO (includes two-axis Part-Speed PSO) • Three-axis PSO (includes three-axis Part-Speed PSO) • Two-axis Part-Speed PSO only (includes one-axis PSO) • Three-axis Part-Speed PSO (includes one-axis PSO)
HyperWire FLEX Connections	1x HyperWire FLEX port
HyperWire Connections	2x HyperWire small form-factor pluggable (SFP) ports
Sync Ports	2x Sync ports
I/O Expansion Board (Optional)	 1x additional PSO connection point 16x digital inputs, optically isolated 16x digital outputs, optically isolated 3x analog inputs, 16-bit, differential, ±10 V 3x analog outputs, 16-bit, single-ended, ±10 V
Internal Motor Supply Capacitance	2400 µf
Maximum Motor Supply External Breaker	20 Amp (Type-D)
Automatic Brake Control	With Automation1 Studio, a discrete digital output must be configured as the automatic brake control output. This requires the -EB1 expansion board on the FLEX Controller. You must wire the axis brake directly from the FLEX Controller (an additional device may be required).
Drive Array Memory	67.1 MB (16,777,216 32-bit elements)
High-Speed Data Capture	Yes (Limitations apply. See controller help files for more information.)
Safe Torque Off (STO)	Please contact Aerotech.
Current Loop Update Rate	20 kHz
Servo Loop Update Rate	10 kHz
Operating Temperature	0 to 40 °C
Storage Temperature	-30 to 85 °C
Weight	1.18 kg (2.60 lb)
Compliance	CE approved, UKCA approved, NRTL safety certification, EU 2015/863 RoHS 3 directive

1. The Automation1 FLEX controller is available with and without an internal Axis Module amplifier power supply. The internal power supply may not provide enough power for your full system. Please consult with Aerotech to see if you need an external power supply for your axis modules.



AUTOMATION1 FLEX AXIS MODULE GENERAL SPECIFICATIONS

CATEGORY		-10	-25		
Motor Style Brushless, brush, voice coil		Brushless, brush, voice coil, stepper ⁽¹⁾			
FLEX	Control Supply	24 VDC			
Controller-Side Connections	Bus Supply ⁽²⁾	0-340 VDC			
	HyperWire FLEX Connections	2x HyperWire FLEX ports			
Axis-Side Motor Supply		0-340 VDC, 4-pin high-powered D-sub connector			
Connections	25-Pin Motor Feedback Connector	 Primary encoder inputs Auxiliary encoder inputs Hall effect sensor inputs (A, B and C) Thermistor motor temperature input (accepts digital) Encoder fault input CW and CCW limits 			
Motor Supply Input Current at Full Output Power		5 A	10 A		
Peak Output Current (1 sec) ^(3,4)		10 A	25 A		
Continuous Output Current ^(3,4,5)		3.5 A _{RMS}	5.3 A _{RMS}		
I/O Port Not yet ava Aerotech fr		Not yet available. Provisions exist to add I/O Aerotech for more information.	t yet available. Provisions exist to add I/O on a FLEX axis module. Please contact rotech for more information.		
Multiplier Options		MX0 Option: Primary Encoder: 40 million counts-per-second square-wave input Auxiliary Encoder: 40 million counts-per-second square-wave input MX2 Option: Primary Encoder: 450 kHz sine-wave input, encoder multiplier up to 65,536 Auxiliary Encoder: 40 million counts per second square-wave input MX3 Option: Primary Encoder: 450 kHz sine-wave input, encoder multiplier up to 65,536 Auxiliary Encoder: 450 kHz sine-wave input, encoder multiplier up to 65,536 Auxiliary Encoder: 450 kHz sine-wave input, encoder multiplier up to x16,384* *Encoders multiplied with this input cannot be echoed out.			
Absolute Encoder		BiSS C Unidirectional; EnDat 2.1; EnDat 2.2; SSI			
Automatic Brake Control		See FLEX Controller specifications.			
Operating Temperature					
Typical Total Power Dissipated by Axis Module ⁽⁶⁾		25W @ 160 VDC 35W @ 320 VDC			
Storage Temperature		-30 to 85 °C			
Weight 0.5 kg(x lb)		0.5 kg(x lb)			
Aerotech Stage Integration		Based on size and thermal considerations, the FLEX axis can be installed on the following Aerotech semi-standard gantry designs: AGS1000, AGS1500, AGS10000, AGS15000. Based on size and thermal considerations, the FLEX axis can be installed on the following Aerotech PRO stages: PRO225, PRO280, PRO560. For other (specifically smaller) stages, the FLEX axis module heat dissipation may be of			
Compliance		greater concern. Please consult with Aerotec CE approved, UKCA approved. NRTL safety co	h for design considerations. ertification, EU 2015/863 RoHS 3 directive		



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- 1. For stepper motors only, one-half of bus voltage is applied across the motor (e.g 80 VDC supply results in 40 VDC across stepper motor).
- 2. Bus supply voltage depends upon the FLEX controller motor supply voltage or upon the user supply bus supply voltage.
- 3. Peak value of the sine wave; rms current for AC motors is 0.707 A_{pk}.
- 4. There are three motor output phases from the drive.
- 5. These values are under full output power. Under a lighter load, the continuous output current capability will be higher.
- 6. Estimated value of heat generated by the FLEX axis module. Actual value will vary based on the application.

HYPERWIRE FLEX COMMUNICATION

CATEGORY				
Physical Layer ⁽¹⁾	Cable Type	High-flex glass optical fiber		
	Cable Bend Radius	30mm		
	Connectors	Small form-factor pluggable		
High-Speed Encoder Feedback Latency		1.6 μs		

1. HyperWire FLEX cables are typically assembled high-flex fiber glass optic cables. For guidance on manufacturing the required cable and connector scheme, please contact Aerotech.















AUTOMATION1 FLEX CONTROLLER WITHOUT MOTOR POWER SUPPLY AND WITH EXPANSION I/O











AUTOMATION1 FLEX AXIS MODULE



